



## **Red Hat Enterprise Linux Release 9.2 Manual Pages on 'systemd.resource-control.5' command**

**\$ man systemd.resource-control.5**

SYSTEMD.RESOURCE-CONTROL(5)systemd.resource-controlSYSTEMD.RESOURCE-CONTROL(5)

### NAME

systemd.resource-control - Resource control unit settings

### SYNOPSIS

slice.slice, scope.scope, service.service, socket.socket, mount.mount,  
swap.swap

### DESCRIPTION

Unit configuration files for services, slices, scopes, sockets, mount points, and swap devices share a subset of configuration options for resource control of spawned processes. Internally, this relies on the Linux Control Groups (cgroups) kernel concept for organizing processes in a hierarchical tree of named groups for the purpose of resource management.

This man page lists the configuration options shared by those six unit types. See `systemd.unit(5)` for the common options of all unit configuration files, and `systemd.slice(5)`, `systemd.scope(5)`, `systemd.service(5)`, `systemd.socket(5)`, `systemd.mount(5)`, and `systemd.swap(5)` for more information on the specific unit configuration files. The resource control configuration options are configured in the [Slice], [Scope], [Service], [Socket], [Mount], or [Swap] sections, depending on the unit type.

In addition, options which control resources available to programs executed by `systemd` are listed in `systemd.exec(5)`. Those options

complement options listed here.

See the New Control Group Interfaces[1] for an introduction on how to make use of resource control APIs from programs.

### Setting resource controls for a group of related units

As described in systemd.unit(5), the settings listed here may be set through the main file of a unit and drop-in snippets in \*.d/ directories. The list of directories searched for drop-ins includes names formed by repeatedly truncating the unit name after all dashes. This is particularly convenient to set resource limits for a group of units with similar names.

For example, every user gets their own slice user-nnn.slice. Drop-ins with local configuration that affect user 1000 may be placed in /etc/systemd/system/user-1000.slice, /etc/systemd/system/user-1000.slice.d/\*.conf, but also /etc/systemd/system/user-.slice.d/\*.conf. This last directory applies to all user slices.

### IMPLICIT DEPENDENCIES

The following dependencies are implicitly added:

? Units with the Slice= setting set automatically acquire Requires= and After= dependencies on the specified slice unit.

### OPTIONS

Units of the types listed above can have settings for resource control configuration:

#### CPUAccounting=

Turn on CPU usage accounting for this unit. Takes a boolean argument. Note that turning on CPU accounting for one unit will also implicitly turn it on for all units contained in the same slice and for all its parent slices and the units contained therein. The system default for this setting may be controlled with DefaultCPUAccounting= in systemd-system.conf(5).

#### CPUWeight=weight, StartupCPUWeight=weight

These options accept an integer value or a the special string "idle":

? If set to an integer value, assign the specified CPU time weight to the processes executed, if the unified control group hierarchy is used on the system. These options control the "cpu.weight" control group attribute. The allowed range is 1 to 10000. Defaults to 100. For details about this control group attribute, see Control Groups v2[2] and CFS Scheduler[3]. The available CPU time is split up among all units within one slice relative to their CPU time weight. A higher weight means more CPU time, a lower weight means less.

? If set to the special string "idle", mark the cgroup for "idle scheduling", which means that it will get CPU resources only when there are no processes not marked in this way to execute in this cgroup or its siblings. This setting corresponds to the "cpu.idle" cgroup attribute.

Note that this value only has an effect on cgroup-v2, for cgroup-v1 it is equivalent to the minimum weight.

While StartupCPUWeight= applies to the startup and shutdown phases of the system, CPUWeight= applies to normal runtime of the system, and if the former is not set also to the startup and shutdown phases. Using StartupCPUWeight= allows prioritizing specific services at boot-up and shutdown differently than during normal runtime.

#### CPUQuota=

Assign the specified CPU time quota to the processes executed.

Takes a percentage value, suffixed with "%". The percentage specifies how much CPU time the unit shall get at maximum, relative to the total CPU time available on one CPU. Use values > 100% for allotting CPU time on more than one CPU. This controls the "cpu.max" attribute on the unified control group hierarchy and "cpu.cfs\_quota\_us" on legacy. For details about these control group attributes, see Control Groups v2[2] and CFS Bandwidth Control[4].

Setting CPUQuota= to an empty value unsets the quota.

Example: CPUQuota=20% ensures that the executed processes will

never get more than 20% CPU time on one CPU.

#### CPUQuotaPeriodSec=

Assign the duration over which the CPU time quota specified by CPUQuota= is measured. Takes a time duration value in seconds, with an optional suffix such as "ms" for milliseconds (or "s" for seconds.) The default setting is 100ms. The period is clamped to the range supported by the kernel, which is [1ms, 1000ms].

Additionally, the period is adjusted up so that the quota interval is also at least 1ms. Setting CPUQuotaPeriodSec= to an empty value resets it to the default.

This controls the second field of "cpu.max" attribute on the unified control group hierarchy and "cpu.cfs\_period\_us" on legacy.

For details about these control group attributes, see Control Groups v2[2] and CFS Scheduler[3].

Example: CPUQuotaPeriodSec=10ms to request that the CPU quota is measured in periods of 10ms.

#### AllowedCPUs=, StartupAllowedCPUs=

Restrict processes to be executed on specific CPUs. Takes a list of CPU indices or ranges separated by either whitespace or commas. CPU ranges are specified by the lower and upper CPU indices separated by a dash.

Setting AllowedCPUs= or StartupAllowedCPUs= doesn't guarantee that all of the CPUs will be used by the processes as it may be limited by parent units. The effective configuration is reported as EffectiveCPUs=.

While StartupAllowedCPUs= applies to the startup and shutdown phases of the system, AllowedCPUs= applies to normal runtime of the system, and if the former is not set also to the startup and shutdown phases. Using StartupAllowedCPUs= allows prioritizing specific services at boot-up and shutdown differently than during normal runtime.

This setting is supported only with the unified control group hierarchy.

AllowedMemoryNodes=, StartupAllowedMemoryNodes=

Restrict processes to be executed on specific memory NUMA nodes.

Takes a list of memory NUMA nodes indices or ranges separated by either whitespace or commas. Memory NUMA nodes ranges are specified by the lower and upper NUMA nodes indices separated by a dash.

Setting AllowedMemoryNodes= or StartupAllowedMemoryNodes= doesn't guarantee that all of the memory NUMA nodes will be used by the processes as it may be limited by parent units. The effective configuration is reported as EffectiveMemoryNodes=.

While StartupAllowedMemoryNodes= applies to the startup and shutdown phases of the system, AllowedMemoryNodes= applies to normal runtime of the system, and if the former is not set also to the startup and shutdown phases. Using StartupAllowedMemoryNodes= allows prioritizing specific services at boot-up and shutdown differently than during normal runtime.

This setting is supported only with the unified control group hierarchy.

MemoryAccounting=

Turn on process and kernel memory accounting for this unit. Takes a boolean argument. Note that turning on memory accounting for one unit will also implicitly turn it on for all units contained in the same slice and for all its parent slices and the units contained therein. The system default for this setting may be controlled with DefaultMemoryAccounting= in systemd-system.conf(5).

MemoryMin=bytes, MemoryLow=bytes

Specify the memory usage protection of the executed processes in this unit. When reclaiming memory, the unit is treated as if it was using less memory resulting in memory to be preferentially reclaimed from unprotected units. Using MemoryLow= results in a weaker protection where memory may still be reclaimed to avoid invoking the OOM killer in case there is no other reclaimable memory.

For a protection to be effective, it is generally required to set a

corresponding allocation on all ancestors, which is then distributed between children (with the exception of the root slice). Any `MemoryMin=` or `MemoryLow=` allocation that is not explicitly distributed to specific children is used to create a shared protection for all children. As this is a shared protection, the children will freely compete for the memory.

Takes a memory size in bytes. If the value is suffixed with K, M, G or T, the specified memory size is parsed as Kilobytes, Megabytes, Gigabytes, or Terabytes (with the base 1024), respectively.

Alternatively, a percentage value may be specified, which is taken relative to the installed physical memory on the system. If assigned the special value "infinity", all available memory is protected, which may be useful in order to always inherit all of the protection afforded by ancestors. This controls the "memory.min" or "memory.low" control group attribute. For details about this control group attribute, see [Memory Interface Files\[5\]](#).

Units may have their children use a default "memory.min" or "memory.low" value by specifying `DefaultMemoryMin=` or `DefaultMemoryLow=`, which has the same semantics as `MemoryMin=` and `MemoryLow=`. This setting does not affect "memory.min" or "memory.low" in the unit itself. Using it to set a default child allocation is only useful on kernels older than 5.7, which do not support the "memory\_recursiveprot" cgroup2 mount option.

#### `MemoryHigh=bytes`

Specify the throttling limit on memory usage of the executed processes in this unit. Memory usage may go above the limit if unavoidable, but the processes are heavily slowed down and memory is taken away aggressively in such cases. This is the main mechanism to control memory usage of a unit.

Takes a memory size in bytes. If the value is suffixed with K, M, G or T, the specified memory size is parsed as Kilobytes, Megabytes, Gigabytes, or Terabytes (with the base 1024), respectively.

Alternatively, a percentage value may be specified, which is taken

relative to the installed physical memory on the system. If assigned the special value "infinity", no memory throttling is applied. This controls the "memory.high" control group attribute. For details about this control group attribute, see Memory Interface Files[5].

#### MemoryMax=bytes

Specify the absolute limit on memory usage of the executed processes in this unit. If memory usage cannot be contained under the limit, out-of-memory killer is invoked inside the unit. It is recommended to use MemoryHigh= as the main control mechanism and use MemoryMax= as the last line of defense.

Takes a memory size in bytes. If the value is suffixed with K, M, G or T, the specified memory size is parsed as Kilobytes, Megabytes, Gigabytes, or Terabytes (with the base 1024), respectively.

Alternatively, a percentage value may be specified, which is taken relative to the installed physical memory on the system. If assigned the special value "infinity", no memory limit is applied.

This controls the "memory.max" control group attribute. For details about this control group attribute, see Memory Interface Files[5].

#### MemorySwapMax=bytes

Specify the absolute limit on swap usage of the executed processes in this unit.

Takes a swap size in bytes. If the value is suffixed with K, M, G or T, the specified swap size is parsed as Kilobytes, Megabytes, Gigabytes, or Terabytes (with the base 1024), respectively. If assigned the special value "infinity", no swap limit is applied.

This controls the "memory.swap.max" control group attribute. For details about this control group attribute, see Memory Interface Files[5].

#### TasksAccounting=

Turn on task accounting for this unit. Takes a boolean argument. If enabled, the system manager will keep track of the number of tasks in the unit. The number of tasks accounted this way includes both

kernel threads and userspace processes, with each thread counting individually. Note that turning on tasks accounting for one unit will also implicitly turn it on for all units contained in the same slice and for all its parent slices and the units contained therein. The system default for this setting may be controlled with `DefaultTasksAccounting=` in `systemd-system.conf(5)`.

#### TasksMax=N

Specify the maximum number of tasks that may be created in the unit. This ensures that the number of tasks accounted for the unit (see above) stays below a specific limit. This either takes an absolute number of tasks or a percentage value that is taken relative to the configured maximum number of tasks on the system. If assigned the special value "infinity", no tasks limit is applied. This controls the "pids.max" control group attribute. For details about this control group attribute, the pids controller[6].

The system default for this setting may be controlled with `DefaultTasksMax=` in `systemd-system.conf(5)`.

#### IOAccounting=

Turn on Block I/O accounting for this unit, if the unified control group hierarchy is used on the system. Takes a boolean argument. Note that turning on block I/O accounting for one unit will also implicitly turn it on for all units contained in the same slice and all for its parent slices and the units contained therein. The system default for this setting may be controlled with `DefaultIOAccounting=` in `systemd-system.conf(5)`.

#### IOWeight=weight, StartupIOWeight=weight

Set the default overall block I/O weight for the executed processes, if the unified control group hierarchy is used on the system. Takes a single weight value (between 1 and 10000) to set the default block I/O weight. This controls the "io.weight" control group attribute, which defaults to 100. For details about this control group attribute, see IO Interface Files[7]. The available I/O bandwidth is split up among all units within one slice relative



to their block I/O weight. A higher weight means more I/O bandwidth, a lower weight means less.

While `StartupIOWeight=` applies to the startup and shutdown phases of the system, `IOWeight=` applies to the later runtime of the system, and if the former is not set also to the startup and shutdown phases. This allows prioritizing specific services at boot-up and shutdown differently than during runtime.

`IODeviceWeight=device weight`

Set the per-device overall block I/O weight for the executed processes, if the unified control group hierarchy is used on the system. Takes a space-separated pair of a file path and a weight value to specify the device specific weight value, between 1 and 10000. (Example: `"/dev/sda 1000"`). The file path may be specified as path to a block device node or as any other file, in which case the backing block device of the file system of the file is determined. This controls the `"io.weight"` control group attribute, which defaults to 100. Use this option multiple times to set weights for multiple devices. For details about this control group attribute, see [IO Interface Files\[7\]](#).

The specified device node should reference a block device that has an I/O scheduler associated, i.e. should not refer to partition or loopback block devices, but to the originating, physical device.

When a path to a regular file or directory is specified it is attempted to discover the correct originating device backing the file system of the specified path. This works correctly only for simpler cases, where the file system is directly placed on a partition or physical block device, or where simple 1:1 encryption using `dm-crypt/LUKS` is used. This discovery does not cover complex storage and in particular RAID and volume management storage devices.

`IOReadBandwidthMax=device bytes, IOWriteBandwidthMax=device bytes`

Set the per-device overall block I/O bandwidth maximum limit for the executed processes, if the unified control group hierarchy is

used on the system. This limit is not work-conserving and the executed processes are not allowed to use more even if the device has idle capacity. Takes a space-separated pair of a file path and a bandwidth value (in bytes per second) to specify the device specific bandwidth. The file path may be a path to a block device node, or as any other file in which case the backing block device of the file system of the file is used. If the bandwidth is suffixed with K, M, G, or T, the specified bandwidth is parsed as Kilobytes, Megabytes, Gigabytes, or Terabytes, respectively, to the base of 1000. (Example:

`"/dev/disk/by-path/pci-0000:00:1f.2-scsi-0:0:0:0 5M"`). This controls the "io.max" control group attributes. Use this option multiple times to set bandwidth limits for multiple devices. For details about this control group attribute, see IO Interface Files[7].

Similar restrictions on block device discovery as for `IODeviceWeight=` apply, see above.

`IOReadIOPSMax=device IOPS, IOWriteIOPSMax=device IOPS`

Set the per-device overall block I/O IOs-Per-Second maximum limit for the executed processes, if the unified control group hierarchy is used on the system. This limit is not work-conserving and the executed processes are not allowed to use more even if the device has idle capacity. Takes a space-separated pair of a file path and an IOPS value to specify the device specific IOPS. The file path may be a path to a block device node, or as any other file in which case the backing block device of the file system of the file is used. If the IOPS is suffixed with K, M, G, or T, the specified IOPS is parsed as KiloIOPS, MegaIOPS, GigaIOPS, or TeraIOPS, respectively, to the base of 1000. (Example:

`"/dev/disk/by-path/pci-0000:00:1f.2-scsi-0:0:0:0 1K"`). This controls the "io.max" control group attributes. Use this option multiple times to set IOPS limits for multiple devices. For details about this control group attribute, see IO Interface Files[7].

Similar restrictions on block device discovery as for

IODeviceWeight= apply, see above.

IODeviceLatencyTargetSec=device target

Set the per-device average target I/O latency for the executed processes, if the unified control group hierarchy is used on the system. Takes a file path and a timespan separated by a space to specify the device specific latency target. (Example: "/dev/sda 25ms"). The file path may be specified as path to a block device node or as any other file, in which case the backing block device of the file system of the file is determined. This controls the "io.latency" control group attribute. Use this option multiple times to set latency target for multiple devices. For details about this control group attribute, see IO Interface Files[7].

Implies "IOAccounting=yes".

These settings are supported only if the unified control group hierarchy is used.

Similar restrictions on block device discovery as for

IODeviceWeight= apply, see above.

IPAccounting=

Takes a boolean argument. If true, turns on IPv4 and IPv6 network traffic accounting for packets sent or received by the unit. When this option is turned on, all IPv4 and IPv6 sockets created by any process of the unit are accounted for.

When this option is used in socket units, it applies to all IPv4 and IPv6 sockets associated with it (including both listening and connection sockets where this applies). Note that for socket-activated services, this configuration setting and the accounting data of the service unit and the socket unit are kept separate, and displayed separately. No propagation of the setting and the collected statistics is done, in either direction.

Moreover, any traffic sent or received on any of the socket unit's sockets is accounted to the socket unit ? and never to the service unit it might have activated, even if the socket is used by it.

The system default for this setting may be controlled with

`DefaultIPAccounting=` in `systemd-system.conf(5)`.

`IPAddressAllow=ADDRESS[/PREFIXLENGTH]...`,

`IPAddressDeny=ADDRESS[/PREFIXLENGTH]...`

Turn on network traffic filtering for IP packets sent and received over `AF_INET` and `AF_INET6` sockets. Both directives take a space separated list of IPv4 or IPv6 addresses, each optionally suffixed with an address prefix length in bits after a "/" character. If the suffix is omitted, the address is considered a host address, i.e. the filter covers the whole address (32 bits for IPv4, 128 bits for IPv6).

The access lists configured with this option are applied to all sockets created by processes of this unit (or in the case of socket units, associated with it). The lists are implicitly combined with any lists configured for any of the parent slice units this unit might be a member of. By default both access lists are empty. Both ingress and egress traffic is filtered by these settings. In case of ingress traffic the source IP address is checked against these access lists, in case of egress traffic the destination IP address is checked. The following rules are applied in turn:

- ? Access is granted when the checked IP address matches an entry in the `IPAddressAllow=` list.
- ? Otherwise, access is denied when the checked IP address matches an entry in the `IPAddressDeny=` list.
- ? Otherwise, access is granted.

In order to implement an allow-listing IP firewall, it is recommended to use a `IPAddressDeny=any` setting on an upper-level slice unit (such as the root slice `-.slice` or the slice containing all system services `system.slice` ? see `systemd.special(7)` for details on these slice units), plus individual per-service `IPAddressAllow=` lines permitting network access to relevant services, and only them.

Note that for socket-activated services, the IP access list

configured on the socket unit applies to all sockets associated with it directly, but not to any sockets created by the ultimately activated services for it. Conversely, the IP access list configured for the service is not applied to any sockets passed into the service via socket activation. Thus, it is usually a good idea to replicate the IP access lists on both the socket and the service unit. Nevertheless, it may make sense to maintain one list more open and the other one more restricted, depending on the usecase.

If these settings are used multiple times in the same unit the specified lists are combined. If an empty string is assigned to these settings the specific access list is reset and all previous settings undone.

In place of explicit IPv4 or IPv6 address and prefix length specifications a small set of symbolic names may be used. The following names are defined:

Table 1. Special address/network names

Symbolic Name	Definition	Meaning
any	0.0.0.0/0 ::0	Any host
localhost	127.0.0.0/8 ::1/128	All addresses on the local loopback
link-local	169.254.0.0/16 fe80::/64	All link-local IP addresses
multicast	224.0.0.0/4 ff00::/8	All IP multicasting addresses

Note that these settings might not be supported on some systems (for example if eBPF control group support is not enabled in the

underlying kernel or container manager). These settings will have no effect in that case. If compatibility with such systems is desired it is hence recommended to not exclusively rely on them for IP security.

IPIngressFilterPath=BPF\_FS\_PROGRAM\_PATH,

IPEgressFilterPath=BPF\_FS\_PROGRAM\_PATH

Add custom network traffic filters implemented as BPF programs, applying to all IP packets sent and received over AF\_INET and AF\_INET6 sockets. Takes an absolute path to a pinned BPF program in the BPF virtual filesystem (/sys/fs/bpf/).

The filters configured with this option are applied to all sockets created by processes of this unit (or in the case of socket units, associated with it). The filters are loaded in addition to filters any of the parent slice units this unit might be a member of as well as any IPAddressAllow= and IPAddressDeny= filters in any of these units. By default there are no filters specified.

If these settings are used multiple times in the same unit all the specified programs are attached. If an empty string is assigned to these settings the program list is reset and all previous specified programs ignored.

If the path BPF\_FS\_PROGRAM\_PATH in IPIngressFilterPath= assignment is already being handled by BPFProgram= ingress hook, e.g.

BPFProgram=ingress:BPF\_FS\_PROGRAM\_PATH, the assignment will be still considered valid and the program will be attached to a cgroup. Same for IPEgressFilterPath= path and egress hook.

Note that for socket-activated services, the IP filter programs configured on the socket unit apply to all sockets associated with it directly, but not to any sockets created by the ultimately activated services for it. Conversely, the IP filter programs configured for the service are not applied to any sockets passed into the service via socket activation. Thus, it is usually a good idea, to replicate the IP filter programs on both the socket and the service unit, however it often makes sense to maintain one

configuration more open and the other one more restricted, depending on the usecase.

Note that these settings might not be supported on some systems (for example if eBPF control group support is not enabled in the underlying kernel or container manager). These settings will fail the service in that case. If compatibility with such systems is desired it is hence recommended to attach your filter manually (requires `Delegate=yes`) instead of using this setting.

`BPFProgram=type:program-path`

Add a custom cgroup BPF program.

`BPFProgram=` allows attaching BPF hooks to the cgroup of a systemd unit. (This generalizes the functionality exposed via `IPEgressFilterPath=` for egress and `IPIngressFilterPath=` for ingress.) Cgroup-bpf hooks in the form of BPF programs loaded to the BPF filesystem are attached with cgroup-bpf attach flags determined by the unit. For details about attachment types and flags see

<https://git.kernel.org/pub/scm/linux/kernel/git/torvalds/linux.git/plain/include/uapi/linux/bpf.h>.

For general BPF documentation please refer to

<https://docs.kernel.org/bpf/index.html>.

The specification of BPF program consists of a type followed by a program-path with ":" as the separator: `type:program-path`.

type is the string name of BPF attach type also used in `bpftool`.

type can be one of `egress`, `ingress`, `sock_create`, `sock_ops`, `device`, `bind4`, `bind6`, `connect4`, `connect6`, `post_bind4`, `post_bind6`, `sendmsg4`, `sendmsg6`, `sysctl`, `recvmsg4`, `recvmsg6`, `getsockopt`, `setsockopt`.

Setting `BPFProgram=` to an empty value makes previous assignments ineffective.

Multiple assignments of the same `type:program-path` value have the same effect as a single assignment: the program with the path `program-path` will be attached to cgroup hook type just once.

If BPF egress pinned to `program-path` path is already being handled by `IPEgressFilterPath=`, `BPFProgram=` assignment will be considered

valid and `BPFProgram=` will be attached to a cgroup. Similarly for ingress hook and `IPIngressFilterPath=` assignment.

BPF programs passed with `BPFProgram=` are attached to the cgroup of a unit with BPF attach flag `multi`, that allows further attachments of the same type within cgroup hierarchy topped by the unit cgroup.

Examples:

```
BPFProgram=egress:/sys/fs/bpf/egress-hook
```

```
BPFProgram=bind6:/sys/fs/bpf/sock-addr-hook
```

`SocketBindAllow=bind-rule`, `SocketBindDeny=bind-rule`

Allow or deny binding a socket address to a socket by matching it with the `bind-rule` and applying a corresponding action if there is a match.

`bind-rule` describes socket properties such as `address-family`, `transport-protocol` and `ip-ports`.

```
bind-rule := { [address-family:][transport-protocol:][ip-ports] | any }
```

```
address-family := { ipv4 | ipv6 }
```

```
transport-protocol := { tcp | udp }
```

```
ip-ports := { ip-port | ip-port-range }
```

An optional `address-family` expects `ipv4` or `ipv6` values. If not specified, a rule will be matched for both IPv4 and IPv6 addresses and applied depending on other socket fields, e.g.

`transport-protocol`, `ip-port`.

An optional `transport-protocol` expects `tcp` or `udp` transport protocol names. If not specified, a rule will be matched for any transport protocol.

An optional `ip-port` value must lie within 1...65535 interval inclusively, i.e. dynamic port 0 is not allowed. A range of sequential ports is described by `ip-port-range :=`

```
ip-port-low-ip-port-high
```

, where `ip-port-low` is smaller than or equal to `ip-port-high` and both are within 1...65535 inclusively.

A special value `any` can be used to apply a rule to any address family, transport protocol and any port with a positive value.



To allow multiple rules assign `SocketBindAllow=` or `SocketBindDeny=` multiple times. To clear the existing assignments pass an empty `SocketBindAllow=` or `SocketBindDeny=` assignment.

For each of `SocketBindAllow=` and `SocketBindDeny=`, maximum allowed number of assignments is 128.

- ? Binding to a socket is allowed when a socket address matches an entry in the `SocketBindAllow=` list.
- ? Otherwise, binding is denied when the socket address matches an entry in the `SocketBindDeny=` list.
- ? Otherwise, binding is allowed.

The feature is implemented with `cgroup/bind4` and `cgroup/bind6` `cgroup-bpf` hooks.

Examples:

```
...
# Allow binding IPv6 socket addresses with a port greater than or equal to 10000.
[Service]
SocketBindAllow=ipv6:10000-65535
SocketBindDeny=any
...
# Allow binding IPv4 and IPv6 socket addresses with 1234 and 4321 ports.
[Service]
SocketBindAllow=1234
SocketBindAllow=4321
SocketBindDeny=any
...
# Deny binding IPv6 socket addresses.
[Service]
SocketBindDeny=ipv6
...
# Deny binding IPv4 and IPv6 socket addresses.
[Service]
SocketBindDeny=any
...
```

```
# Allow binding only over TCP
```

```
[Service]
```

```
SocketBindAllow=tcp
```

```
SocketBindDeny=any
```

```
...
```

```
# Allow binding only over IPv6/TCP
```

```
[Service]
```

```
SocketBindAllow=ipv6:tcp
```

```
SocketBindDeny=any
```

```
...
```

```
# Allow binding ports within 10000-65535 range over IPv4/UDP.
```

```
[Service]
```

```
SocketBindAllow=ipv4:udp:10000-65535
```

```
SocketBindDeny=any
```

```
...
```

RestrictNetworkInterfaces=

Takes a list of space-separated network interface names. This option restricts the network interfaces that processes of this unit can use. By default processes can only use the network interfaces listed (allow-list). If the first character of the rule is "~", the effect is inverted: the processes can only use network interfaces not listed (deny-list).

This option can appear multiple times, in which case the network interface names are merged. If the empty string is assigned the set is reset, all prior assignments will have no effect.

If you specify both types of this option (i.e. allow-listing and deny-listing), the first encountered will take precedence and will dictate the default action (allow vs deny). Then the next occurrences of this option will add or delete the listed network interface names from the set, depending on its type and the default action.

The loopback interface ("lo") is not treated in any special way, you have to configure it explicitly in the unit file.

Example 1: allow-list

```
RestrictNetworkInterfaces=eth1
```

```
RestrictNetworkInterfaces=eth2
```

Programs in the unit will be only able to use the eth1 and eth2 network interfaces.

Example 2: deny-list

```
RestrictNetworkInterfaces=~eth1 eth2
```

Programs in the unit will be able to use any network interface but eth1 and eth2.

Example 3: mixed

```
RestrictNetworkInterfaces=eth1 eth2
```

```
RestrictNetworkInterfaces=~eth1
```

Programs in the unit will be only able to use the eth2 network interface.

DeviceAllow=

Control access to specific device nodes by the executed processes.

Takes two space-separated strings: a device node specifier followed by a combination of r, w, m to control reading, writing, or creation of the specific device nodes by the unit (mknod), respectively. This functionality is implemented using eBPF filtering.

When access to all physical devices should be disallowed, PrivateDevices= may be used instead. See systemd.exec(5).

The device node specifier is either a path to a device node in the file system, starting with /dev/, or a string starting with either "char-" or "block-" followed by a device group name, as listed in /proc/devices. The latter is useful to allow-list all current and future devices belonging to a specific device group at once. The device group is matched according to filename globbing rules, you may hence use the "\*" and "?" wildcards. (Note that such globbing wildcards are not available for device node path specifications!)

In order to match device nodes by numeric major/minor, use device node paths in the /dev/char/ and /dev/block/ directories. However,

matching devices by major/minor is generally not recommended as assignments are neither stable nor portable between systems or different kernel versions.

Examples: `/dev/sda5` is a path to a device node, referring to an ATA or SCSI block device. `"char-pts"` and `"char-alsa"` are specifiers for all pseudo TTYs and all ALSA sound devices, respectively.

`"char-cpu/*"` is a specifier matching all CPU related device groups.

Note that allow lists defined this way should only reference device groups which are resolvable at the time the unit is started. Any device groups not resolvable then are not added to the device allow list. In order to work around this limitation, consider extending service units with a pair of `After=modprobe@xyz.service` and `Wants=modprobe@xyz.service` lines that load the necessary kernel module implementing the device group if missing. Example:

```
...  
[Unit]  
Wants=modprobe@loop.service  
After=modprobe@loop.service  
[Service]  
DeviceAllow=block-loop  
DeviceAllow=/dev/loop-control  
...
```

`DevicePolicy=auto|closed|strict`

Control the policy for allowing device access:

`strict`

means to only allow types of access that are explicitly specified.

`closed`

in addition, allows access to standard pseudo devices including `/dev/null`, `/dev/zero`, `/dev/full`, `/dev/random`, and `/dev/urandom`.

`auto`

in addition, allows access to all devices if no explicit

`DeviceAllow=` is present. This is the default.

## Slice=

The name of the slice unit to place the unit in. Defaults to `system.slice` for all non-instantiated units of all unit types (except for slice units themselves see below). Instance units are by default placed in a subslice of `system.slice` that is named after the template name.

This option may be used to arrange `systemd` units in a hierarchy of slices each of which might have resource settings applied.

For units of type `slice`, the only accepted value for this setting is the parent slice. Since the name of a slice unit implies the parent slice, it is hence redundant to ever set this parameter directly for slice units.

Special care should be taken when relying on the default slice assignment in templated service units that have `DefaultDependencies=no` set, see `systemd.service(5)`, section "Default Dependencies" for details.

## Delegate=

Turns on delegation of further resource control partitioning to processes of the unit. Units where this is enabled may create and manage their own private subhierarchy of control groups below the control group of the unit itself. For unprivileged services (i.e. those using the `User=` setting) the unit's control group will be made accessible to the relevant user. When enabled the service manager will refrain from manipulating control groups or moving processes below the unit's control group, so that a clear concept of ownership is established: the control group tree above the unit's control group (i.e. towards the root control group) is owned and managed by the service manager of the host, while the control group tree below the unit's control group is owned and managed by the unit itself. Takes either a boolean argument or a list of control group controller names. If true, delegation is turned on, and all supported controllers are enabled for the unit, making them available to the unit's processes for management. If false,

delegation is turned off entirely (and no additional controllers are enabled). If set to a list of controllers, delegation is turned on, and the specified controllers are enabled for the unit. Note that additional controllers than the ones specified might be made available as well, depending on configuration of the containing slice unit or other units contained in it. Note that assigning the empty string will enable delegation, but reset the list of controllers, all assignments prior to this will have no effect.

Defaults to false.

Note that controller delegation to less privileged code is only safe on the unified control group hierarchy. Accordingly, access to the specified controllers will not be granted to unprivileged services on the legacy hierarchy, even when requested.

The following controller names may be specified: `cpu`, `cpuacct`, `cpuset`, `io`, `blkio`, `memory`, `devices`, `pids`, `bpf-firewall`, and `bpf-devices`.

Not all of these controllers are available on all kernels however, and some are specific to the unified hierarchy while others are specific to the legacy hierarchy. Also note that the kernel might support further controllers, which aren't covered here yet as delegation is either not supported at all for them or not defined cleanly.

For further details on the delegation model consult Control Group APIs and Delegation[8].

`DisableControllers=`

Disables controllers from being enabled for a unit's children. If a controller listed is already in use in its subtree, the controller will be removed from the subtree. This can be used to avoid child units being able to implicitly or explicitly enable a controller.

Defaults to not disabling any controllers.

It may not be possible to successfully disable a controller if the unit or any child of the unit in question delegates controllers to its children, as any delegated subtree of the cgroup hierarchy is

unmanaged by systemd.

Multiple controllers may be specified, separated by spaces. You may also pass `DisableControllers=` multiple times, in which case each new instance adds another controller to disable. Passing `DisableControllers=` by itself with no controller name present resets the disabled controller list.

The following controller names may be specified: `cpu`, `cpuacct`, `cpuset`, `io`, `blkio`, `memory`, `devices`, `pids`, `bpf-firewall`, and `bpf-devices`.

`ManagedOOMSwap=auto|kill`, `ManagedOOMMemoryPressure=auto|kill`

Specifies how `systemd-oomd.service(8)` will act on this unit's cgroups. Defaults to `auto`.

When set to `kill`, the unit becomes a candidate for monitoring by `systemd-oomd`. If the cgroup passes the limits set by `oomd.conf(5)` or the unit configuration, `systemd-oomd` will select a descendant cgroup and send `SIGKILL` to all of the processes under it. You can find more details on candidates and kill behavior at `systemd-oomd.service(8)` and `oomd.conf(5)`.

Setting either of these properties to `kill` will also result in `After=` and `Wants=` dependencies on `systemd-oomd.service` unless `DefaultDependencies=no`.

When set to `auto`, `systemd-oomd` will not actively use this cgroup's data for monitoring and detection. However, if an ancestor cgroup has one of these properties set to `kill`, a unit with `auto` can still be a candidate for `systemd-oomd` to terminate.

`ManagedOOMMemoryPressureLimit=`

Overrides the default memory pressure limit set by `oomd.conf(5)` for this unit (cgroup). Takes a percentage value between 0% and 100%, inclusive. This property is ignored unless `ManagedOOMMemoryPressure=kill`. Defaults to 0%, which means to use the default set by `oomd.conf(5)`.

`ManagedOOMPreference=none|avoid|omit`

Allows deprioritizing or omitting this unit's cgroup as a candidate

when systemd-oomd needs to act. Requires support for extended attributes (see `xattr(7)`) in order to use `avoid` or `omit`.

When calculating candidates to relieve swap usage, systemd-oomd will only respect these extended attributes if the unit's cgroup is owned by root.

When calculating candidates to relieve memory pressure, systemd-oomd will only respect these extended attributes if the unit's cgroup owner, and the owner of the monitored ancestor cgroup are the same. For example, if systemd-oomd is calculating candidates for `-.slice`, then extended attributes set on descendants of `/user.slice/user-1000.slice/user@1000.service/` will be ignored because the descendants are owned by UID 1000, and `-.slice` is owned by UID 0. But, if calculating candidates for `/user.slice/user-1000.slice/user@1000.service/`, then extended attributes set on the descendants would be respected.

If this property is set to `avoid`, the service manager will convey this to systemd-oomd, which will only select this cgroup if there are no other viable candidates.

If this property is set to `omit`, the service manager will convey this to systemd-oomd, which will ignore this cgroup as a candidate and will not perform any actions on it.

It is recommended to use `avoid` and `omit` sparingly, as it can adversely affect systemd-oomd's kill behavior. Also note that these extended attributes are not applied recursively to cgroups under this unit's cgroup.

Defaults to `none` which means systemd-oomd will rank this unit's cgroup as defined in `systemd-oomd.service(8)` and `oomd.conf(5)`.

## HISTORY

systemd 252

Options for controlling the Legacy Control Group Hierarchy (Control Groups version 1[9]) are now fully deprecated: `CPUShares=weight`, `StartupCPUShares=weight`, `MemoryLimit=bytes`, `BlockIOAccounting=`, `BlockIOWeight=weight`, `StartupBlockIOWeight=weight`,



BlockIODeviceWeight=device weight, BlockIOReadBandwidth=device bytes, BlockIOWriteBandwidth=device bytes. Please switch to the unified cgroup hierarchy.

## SEE ALSO

systemd(1), systemd-system.conf(5), systemd.unit(5), systemd.service(5), systemd.slice(5), systemd.scope(5), systemd.socket(5), systemd.mount(5), systemd.swap(5), systemd.exec(5), systemd.directives(7), systemd.special(7), systemd-oomd.service(8), The documentation for control groups and specific controllers in the Linux kernel: Control Groups v2[2].

## NOTES

### 1. New Control Group Interfaces

<https://www.freedesktop.org/wiki/Software/systemd/ControlGroupInterface>

### 2. Control Groups v2

<https://docs.kernel.org/admin-guide/cgroup-v2.html>

### 3. CFS Scheduler

<https://docs.kernel.org/scheduler/sched-design-CFS.html>

### 4. CFS Bandwidth Control

<https://docs.kernel.org/scheduler/sched-bwc.html>

### 5. Memory Interface Files

<https://docs.kernel.org/admin-guide/cgroup-v2.html#memory-interface-files>

### 6. pids controller

<https://www.kernel.org/doc/html/latest/admin-guide/cgroup-v2.html#pid>

### 7. IO Interface Files

<https://docs.kernel.org/admin-guide/cgroup-v2.html#io-interface-files>

### 8. Control Group APIs and Delegation

[https://systemd.io/CGROUP\\_DELEGATION](https://systemd.io/CGROUP_DELEGATION)

### 9. Control Groups version 1

<https://docs.kernel.org/admin-guide/cgroup-v1/index.html>