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# Red Hat Enterprise Linux Release 9.2 Manual Pages on 'adjtimex.2' command

# \$ man adjtimex.2

ADJTIMEX(2) Linux Programmer's Manual

ADJTIMEX(2)

# NAME

adjtimex, clock\_adjtime, ntp\_adjtime - tune kernel clock

# **SYNOPSIS**

#include <sys/timex.h>

int adjtimex(struct timex \*buf);

int clock\_adjtime(clockid\_t clk\_id, struct timex \*buf);

int ntp\_adjtime(struct timex \*buf);

### DESCRIPTION

Linux uses David L. Mills' clock adjustment algorithm (see RFC 5905).

The system call adjtimex() reads and optionally sets adjustment parame?

ters for this algorithm. It takes a pointer to a timex structure, up?

dates kernel parameters from (selected) field values, and returns the

same structure updated with the current kernel values. This structure

is declared as follows:

struct timex {

int modes: /\* Mode selector \*/

long offset; /\* Time offset; nanoseconds, if STA\_NANO

status flag is set, otherwise

microseconds \*/

long freq; /\* Frequency offset; see NOTES for units \*/

long maxerror; /\* Maximum error (microseconds) \*/

long esterror; /\* Estimated error (microseconds) \*/

int status; /\* Clock command/status \*/

long constant; /\* PLL (phase-locked loop) time constant \*/

long precision; /\* Clock precision

(microseconds, read-only) \*/

long tolerance; /\* Clock frequency tolerance (read-only);

see NOTES for units \*/

struct timeval time;

- /\* Current time (read-only, except for ADJ\_SETOFFSET); upon return, time.tv\_usec contains nanoseconds, if STA\_NANO status flag is set, otherwise microseconds \*/
- long tick; /\* Microseconds between clock ticks \*/
- long ppsfreq; /\* PPS (pulse per second) frequency (read-only); see NOTES for units \*/
- long jitter; /\* PPS jitter (read-only); nanoseconds, if STA\_NANO status flag is set, otherwise microseconds \*/
- int shift; /\* PPS interval duration (seconds, read-only) \*/
- long stabil; /\* PPS stability (read-only); see NOTES for units \*/
- long jitcnt; /\* PPS count of jitter limit exceeded events (read-only) \*/
- long calcnt; /\* PPS count of calibration intervals (read-only) \*/
- long errcnt; /\* PPS count of calibration errors (read-only) \*/
- long stbcnt; /\* PPS count of stability limit exceeded events (read-only) \*/
- int tai; /\* TAI offset, as set by previous ADJ\_TAI operation (seconds, read-only, since Linux 2.6.26) \*/

/\* Further padding bytes to allow for future expansion \*/

};

The modes field determines which parameters, if any, to set. (As de? scribed later in this page, the constants used for ntp\_adjtime() are equivalent but differently named.) It is a bit mask containing a bit? wise-or combination of zero or more of the following bits:

#### ADJ\_OFFSET

Set time offset from buf.offset. Since Linux 2.6.26, the sup? plied value is clamped to the range (-0.5s, +0.5s). In older kernels, an EINVAL error occurs if the supplied value is out of range.

#### ADJ\_FREQUENCY

Set frequency offset from buf.freq. Since Linux 2.6.26, the supplied value is clamped to the range (-32768000, +32768000). In older kernels, an EINVAL error occurs if the supplied value is out of range.

### ADJ\_MAXERROR

Set maximum time error from buf.maxerror.

### ADJ\_ESTERROR

Set estimated time error from buf.esterror.

#### ADJ\_STATUS

Set clock status bits from buf.status. A description of these

bits is provided below.

### ADJ\_TIMECONST

Set PLL time constant from buf.constant. If the STA\_NANO status

flag (see below) is clear, the kernel adds 4 to this value.

### ADJ\_SETOFFSET (since Linux 2.6.39)

Add buf.time to the current time. If buf.status includes the ADJ\_NANO flag, then buf.time.tv\_usec is interpreted as a nanosecond value; otherwise it is interpreted as microseconds. The value of buf.time is the sum of its two fields, but the field buf.time.tv\_usec must always be nonnegative. The follow? ing example shows how to normalize a timeval with nanosecond resolution.

```
while (buf.time.tv_usec < 0) {</pre>
```

buf.time.tv\_sec -= 1;

buf.time.tv\_usec += 100000000;

}

ADJ\_MICRO (since Linux 2.6.26)

Select microsecond resolution.

ADJ\_NANO (since Linux 2.6.26)

Select nanosecond resolution. Only one of ADJ\_MICRO and

ADJ\_NANO should be specified.

ADJ\_TAI (since Linux 2.6.26)

Set TAI (Atomic International Time) offset from buf.constant.

ADJ\_TAI should not be used in conjunction with ADJ\_TIMECONST,

since the latter mode also employs the buf.constant field.

For a complete explanation of TAI and the difference between TAI

and UTC, see BIPM ?http://www.bipm.org/en/bipm/tai/tai.html?

ADJ\_TICK

Set tick value from buf.tick.

Alternatively, modes can be specified as either of the following

(multibit mask) values, in which case other bits should not be speci?

fied in modes:

# ADJ\_OFFSET\_SINGLESHOT

Old-fashioned adjtime(3): (gradually) adjust time by value spec? ified in buf.offset, which specifies an adjustment in microsec? onds.

ADJ\_OFFSET\_SS\_READ (functional since Linux 2.6.28)

Return (in buf.offset) the remaining amount of time to be ad? justed after an earlier ADJ\_OFFSET\_SINGLESHOT operation. This feature was added in Linux 2.6.24, but did not work correctly until Linux 2.6.28.

Ordinary users are restricted to a value of either 0 or ADJ\_OFF?

SET\_SS\_READ for modes. Only the superuser may set any parameters.

The buf.status field is a bit mask that is used to set and/or retrieve

status bits associated with the NTP implementation. Some bits in the

mask are both readable and settable, while others are read-only.

STA\_PLL (read-write)

Enable phase-locked loop (PLL) updates via ADJ\_OFFSET.

### STA\_PPSFREQ (read-write)

Enable PPS (pulse-per-second) frequency discipline.

### STA\_PPSTIME (read-write)

Enable PPS time discipline.

# STA\_FLL (read-write)

Select frequency-locked loop (FLL) mode.

# STA\_INS (read-write)

Insert a leap second after the last second of the UTC day, thus extending the last minute of the day by one second. Leap-second insertion will occur each day, so long as this flag remains set.

# STA\_DEL (read-write)

Delete a leap second at the last second of the UTC day. Leap second deletion will occur each day, so long as this flag re? mains set.

### STA\_UNSYNC (read-write)

Clock unsynchronized.

# STA\_FREQHOLD (read-write)

Hold frequency. Normally adjustments made via ADJ\_OFFSET result in dampened frequency adjustments also being made. So a single call corrects the current offset, but as offsets in the same di? rection are made repeatedly, the small frequency adjustments will accumulate to fix the long-term skew.

This flag prevents the small frequency adjustment from being

made when correcting for an ADJ\_OFFSET value.

### STA\_PPSSIGNAL (read-only)

A valid PPS (pulse-per-second) signal is present.

# STA\_PPSJITTER (read-only)

PPS signal jitter exceeded.

# STA\_PPSWANDER (read-only)

PPS signal wander exceeded.

### STA\_PPSERROR (read-only)

PPS signal calibration error.

### STA\_CLOCKERR (read-only)

Clock hardware fault.

```
STA_NANO (read-only; since Linux 2.6.26)
```

Resolution (0 = microsecond, 1 = nanoseconds). Set via

ADJ\_NANO, cleared via ADJ\_MICRO.

### STA\_MODE (since Linux 2.6.26)

Mode (0 = Phase Locked Loop, 1 = Frequency Locked Loop).

STA\_CLK (read-only; since Linux 2.6.26)

Clock source (0 = A, 1 = B); currently unused.

Attempts to set read-only status bits are silently ignored.

### clock\_adjtime ()

The clock\_adjtime() system call (added in Linux 2.6.39) behaves like

adjtimex() but takes an additional clk\_id argument to specify the par?

ticular clock on which to act.

### ntp\_adjtime ()

The ntp\_adjtime() library function (described in the NTP "Kernel Appli? cation Program API", KAPI) is a more portable interface for performing the same task as adjtimex(). Other than the following points, it is identical to adjtimex():

- \* The constants used in modes are prefixed with "MOD\_" rather than "ADJ\_", and have the same suffixes (thus, MOD\_OFFSET, MOD\_FREQUENCY, and so on), other than the exceptions noted in the following points.
- \* MOD\_CLKA is the synonym for ADJ\_OFFSET\_SINGLESHOT.
- \* MOD\_CLKB is the synonym for ADJ\_TICK.
- \* The is no synonym for ADJ\_OFFSET\_SS\_READ, which is not described in the KAPI.

# **RETURN VALUE**

On success, adjtimex() and ntp\_adjtime() return the clock state; that

is, one of the following values:

- TIME\_OK Clock synchronized, no leap second adjustment pending.
- TIME\_INS Indicates that a leap second will be added at the end of

the UTC day.

TIME\_DEL Indicates that a leap second will be deleted at the end of the UTC day.

TIME\_OOP Insertion of a leap second is in progress.

TIME\_WAIT A leap-second insertion or deletion has been completed. This value will be returned until the next ADJ\_STATUS oper? ation clears the STA\_INS and STA\_DEL flags.

TIME\_ERROR The system clock is not synchronized to a reliable server.

This value is returned when any of the following holds

true:

- \* Either STA\_UNSYNC or STA\_CLOCKERR is set.
- \* STA\_PPSSIGNAL is clear and either STA\_PPSFREQ or STA\_PP? STIME is set.
- \* STA\_PPSTIME and STA\_PPSJITTER are both set.
- \* STA\_PPSFREQ is set and either STA\_PPSWANDER or STA\_PP? SJITTER is set.

The symbolic name TIME\_BAD is a synonym for TIME\_ERROR,

provided for backward compatibility.

Note that starting with Linux 3.4, the call operates asynchronously and

the return value usually will not reflect a state change caused by the

call itself.

On failure, these calls return -1 and set errno.

### ERRORS

EFAULT buf does not point to writable memory.

EINVAL (kernels before Linux 2.6.26)

An attempt was made to set buf.freq to a value outside the range

(-33554432, +33554432).

EINVAL (kernels before Linux 2.6.26)

An attempt was made to set buf.offset to a value outside the permitted range. In kernels before Linux 2.0, the permitted range was (-131072, +131072). From Linux 2.0 onwards, the per? mitted range was (-512000, +512000).

EINVAL An attempt was made to set buf.status to a value other than

those listed above.

- EINVAL The clk\_id given to clock\_adjtime() is invalid for one of two reasons. Either the System-V style hard-coded positive clock ID value is out of range, or the dynamic clk\_id does not refer to a valid instance of a clock object. See clock\_gettime(2) for a discussion of dynamic clocks.
- EINVAL An attempt was made to set buf.tick to a value outside the range 900000/HZ to 1100000/HZ, where HZ is the system timer interrupt frequency.
- ENODEV The hot-pluggable device (like USB for example) represented by a dynamic clk\_id has disappeared after its character device was opened. See clock\_gettime(2) for a discussion of dynamic clocks.

### EOPNOTSUPP

The given clk\_id does not support adjustment.

EPERM buf.modes is neither 0 nor ADJ\_OFFSET\_SS\_READ, and the caller

does not have sufficient privilege. Under Linux, the

CAP\_SYS\_TIME capability is required.

# ATTRIBUTES

For an explanation of the terms used in this section, see at?

tributes(7).

?Interface ? Attribute ? Value ?

?ntp\_adjtime() ? Thread safety ? MT-Safe ?

### CONFORMING TO

None of these interfaces is described in POSIX.1

adjtimex() and clock\_adjtime() are Linux-specific and should not be

used in programs intended to be portable.

The preferred API for the NTP daemon is ntp\_adjtime().

### NOTES

In struct timex, freq, ppsfreq, and stabil are ppm (parts per million)

with a 16-bit fractional part, which means that a value of 1 in one of those fields actually means 2^-16 ppm, and 2^16=65536 is 1 ppm. This is the case for both input values (in the case of freq) and output val? ues.

The leap-second processing triggered by STA\_INS and STA\_DEL is done by the kernel in timer context. Thus, it will take one tick into the sec? ond for the leap second to be inserted or deleted.

# SEE ALSO

clock\_gettime(2), clock\_settime(2), settimeofday(2), adjtime(3),

ntp\_gettime(3), capabilities(7), time(7), adjtimex(8), hwclock(8)

NTP "Kernel Application Program Interface"

?http://www.slac.stanford.edu/comp/unix/package/rtems/src/ssrlApps/

ntpNanoclock/api.htm?

# COLOPHON

This page is part of release 5.10 of the Linux man-pages project. A

description of the project, information about reporting bugs, and the

latest version of this page, can be found at

https://www.kernel.org/doc/man-pages/.

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