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Rocky Enterprise Linux 9.2 Manual Pages on command '\_\_ppc\_set\_ppr\_med\_low.3'

\$ manppc_set_ppr_med_low.	3	
PPC_SET_PPR_MED(3)	LinuxProgrammer's Manual	PPC_SET_PPR_MED(3)
NAME		
ppc_set_ppr_med,ppc_	set_ppr_very_low,ppc_set_ppr	_low,ppc_set_ppr_med_low,
ppc_set_ppr_med_high - Se	et the Program Priority Register	
SYNOPSIS		
#include <sys platform="" ppc.h=""></sys>		
voidppc_set_ppr_med(void)	);	
voidppc_set_ppr_very_low(	(void);	
voidppc_set_ppr_low(void);		
voidppc_set_ppr_med_low(	(void);	
voidppc_set_ppr_med_high	n(void);	
DESCRIPTION		

These functions provide access to the Program Priority Register (PPR) on the Power archi? tecture.

The PPR is a 64-bit register that controls the program's priority. By adjusting the PPR value the programmer may improve system throughput by causing system resources to be used more efficiently, especially in contention situations. The available unprivileged states are covered by the following functions:

- \_\_ppc\_set\_ppr\_med() sets the Program Priority Register value to medium (default).
- \* \_\_ppc\_set\_ppr\_very\_low() sets the Program Priority Register value to very low.
- \* \_\_ppc\_set\_ppr\_low() sets the Program Priority Register value to low.
- \* \_\_ppc\_set\_ppr\_med\_low() sets the Program Priority Register value to medium low.

state (unprivileged) programs, with the following function:

\* \_\_ppc\_set\_ppr\_med\_high() sets the Program Priority to medium high.

If the program priority is medium high when the time interval expires or if an attempt is made to set the priority to medium high when it is not allowed, the priority is set to medium.

### **VERSIONS**

```
The functions __ppc_set_ppr_med(), __ppc_set_ppr_low(), and __ppc_set_ppr_med_low() are provided by glibc since version 2.18. The functions __ppc_set_ppr_very_low() and __ppc_set_ppr_med_high() first appeared in glibc in version 2.23.
```

### **ATTRIBUTES**

For an explanation of the terms used in this section, see attributes(7).

?Interface ? Attribute ? Value ?

?\_\_ppc\_set\_ppr\_med(), ? Thread safety ? MT-Safe ?

?\_\_ppc\_set\_ppr\_very\_low(), ? ? ?

?\_\_ppc\_set\_ppr\_low(), ? ? ?

?\_\_ppc\_set\_ppr\_med\_low(), ? ? ?

? ppc set ppr med high() ? ? ?

## **CONFORMING TO**

These functions are nonstandard GNU extensions.

# **NOTES**

The functions \_\_ppc\_set\_ppr\_very\_low() and \_\_ppc\_set\_ppr\_med\_high() will be defined by <sys/platform/ppc.h> if \_ARCH\_PWR8 is defined. Availability of these functions can be tested using #ifdef \_ARCH\_PWR8.

### SEE ALSO

\_\_ppc\_yield(3)

Power ISA, Book II - Section 3.1 (Program Priority Registers)

### **COLOPHON**

This page is part of release 5.10 of the Linux man-pages project. A description of the project, information about reporting bugs, and the latest version of this page, can be found at https://www.kernel.org/doc/man-pages/.